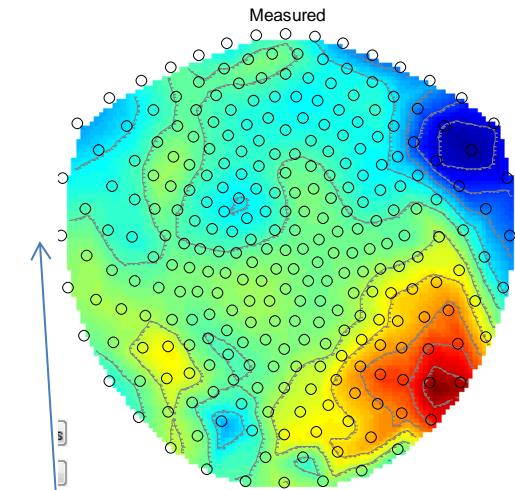


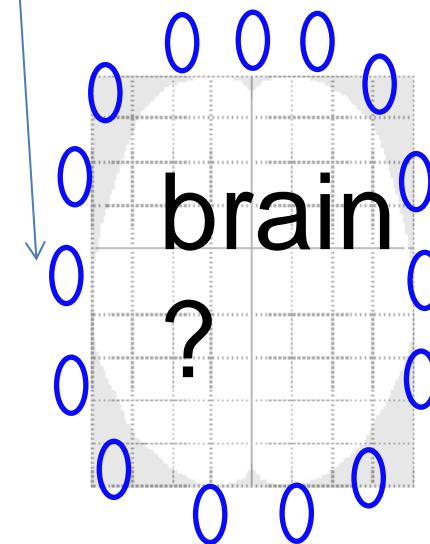
The M/EEG inverse problem

Gareth R. Barnes

Measurement (Y)



M/EEG sensors



Prior info

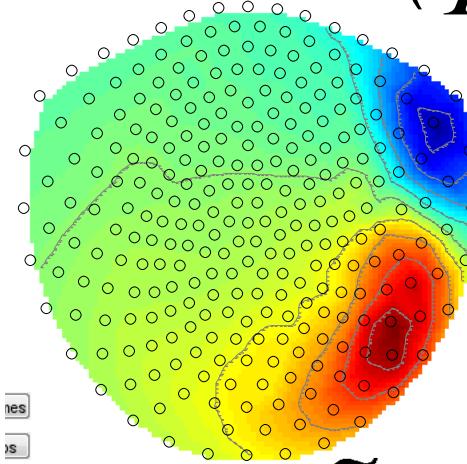
Current density Estimate

$$\tilde{J} = WY$$

Inverse problem

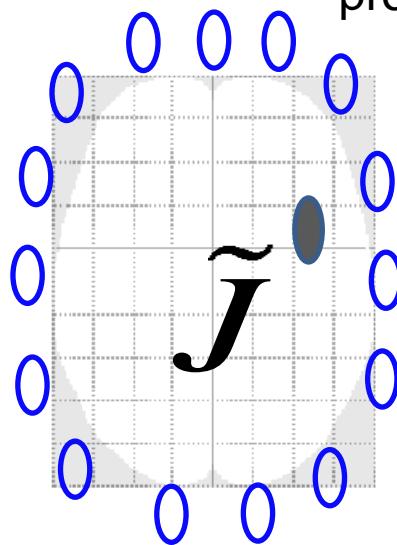


Prediction (\hat{Y})



$$\uparrow \tilde{Y} = L\tilde{J}$$

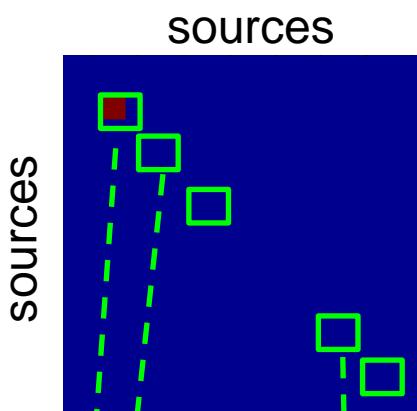
Forward problem



Inversion depends on choice of source covariance matrix
(prior information)

$$W = C \mathbf{L} (\mathbf{R} + \mathbf{L} C \mathbf{L})^{-1}$$

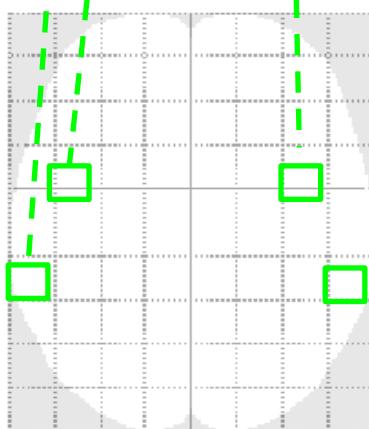
Source covariance
matrix,
One diagonal
element per source



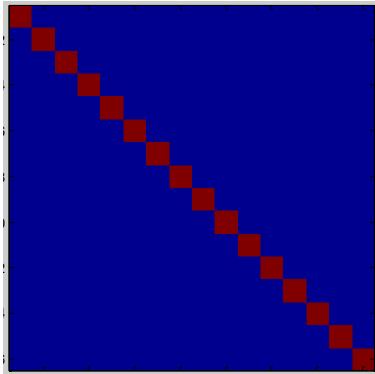
Sensor Noise
(known)

Lead field
(known)

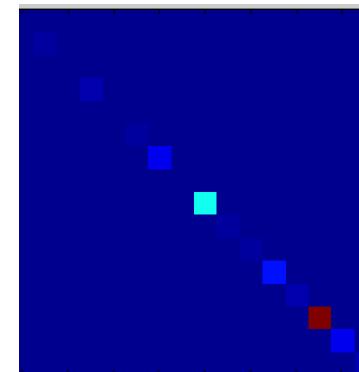
Prior information



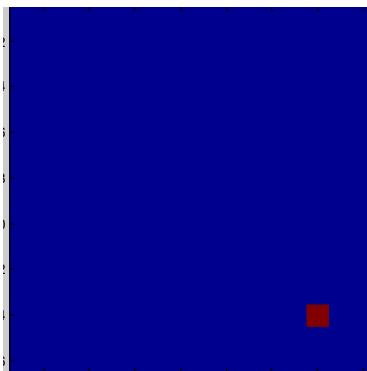
Some popular priors



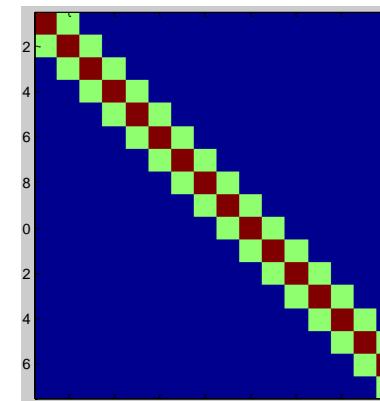
Minimum norm



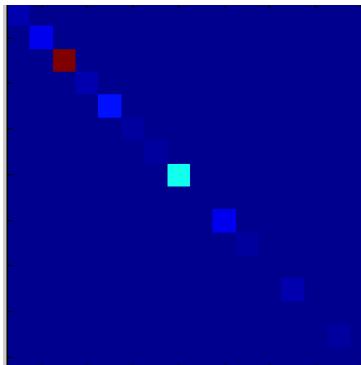
SAM,DICs
Beamformer



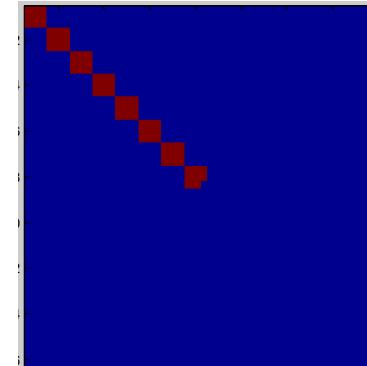
Dipole fit



LORETA



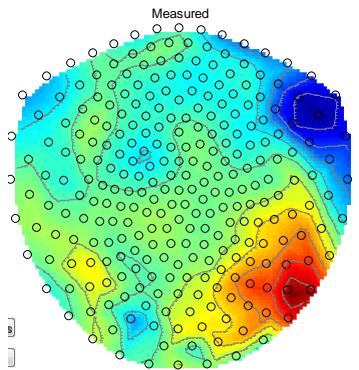
fMRI biased
dSPM



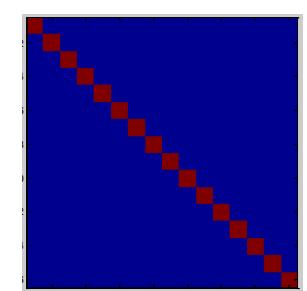
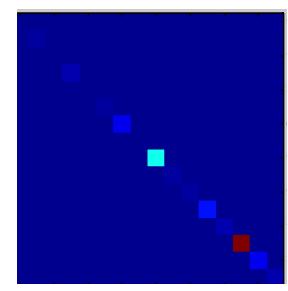
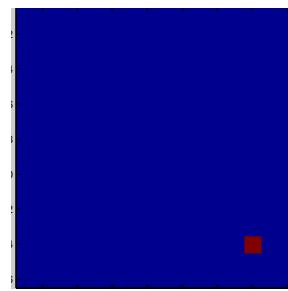
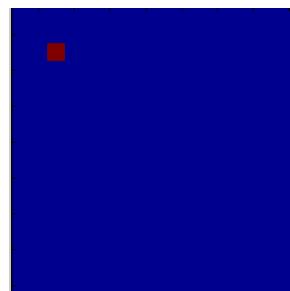
?

Y (measured field)

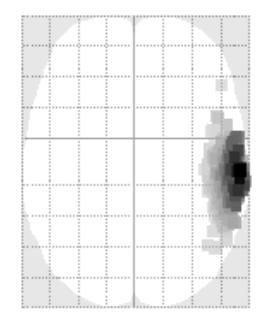
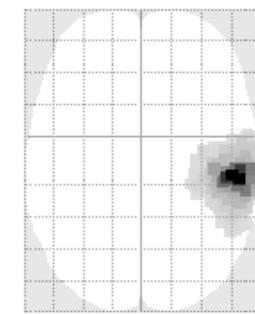
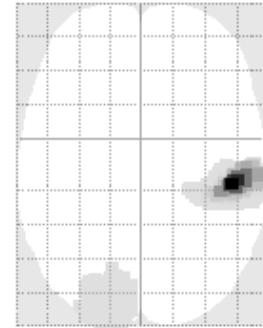
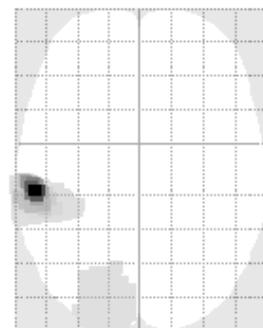
How do we chose between priors ?



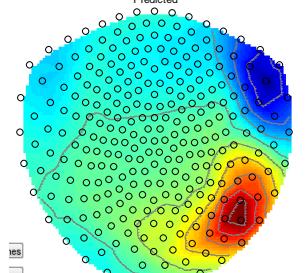
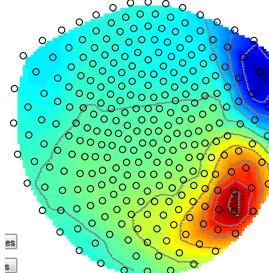
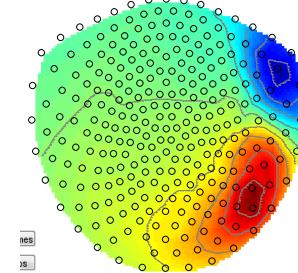
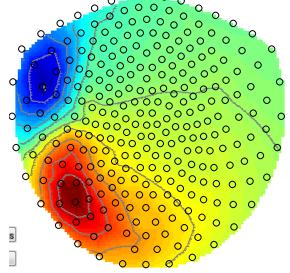
Prior



\tilde{J}



\tilde{Y}



Variance explained

11 %

96%

97%

98%

Use prior info (possible ingredients)



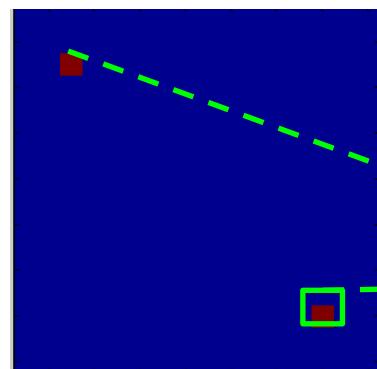
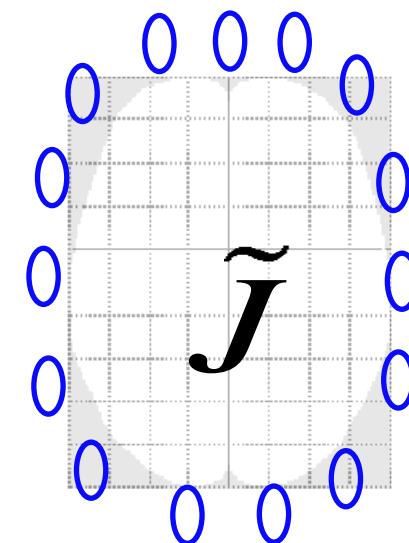
Measurement (Y)



\tilde{Y}

Prediction (\hat{Y})

Forward problem

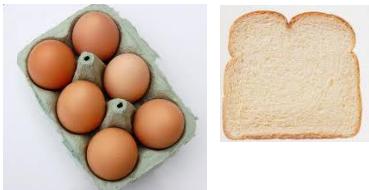


Inverse problem
Prior info (source covariance)

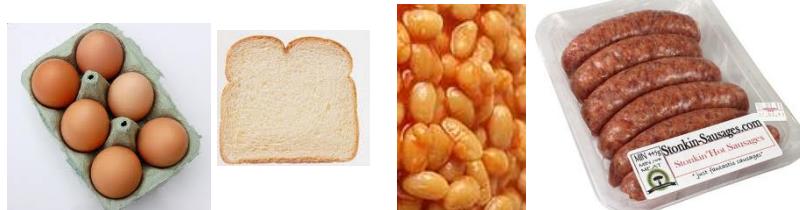
Diagonal elements correspond to ingredients

Possible priors

A



B



C



Which is most likely prior (which prior has highest evidence) ?

\tilde{Y}

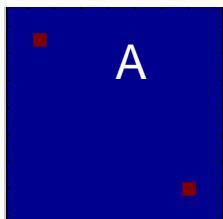


Measurement (Y)

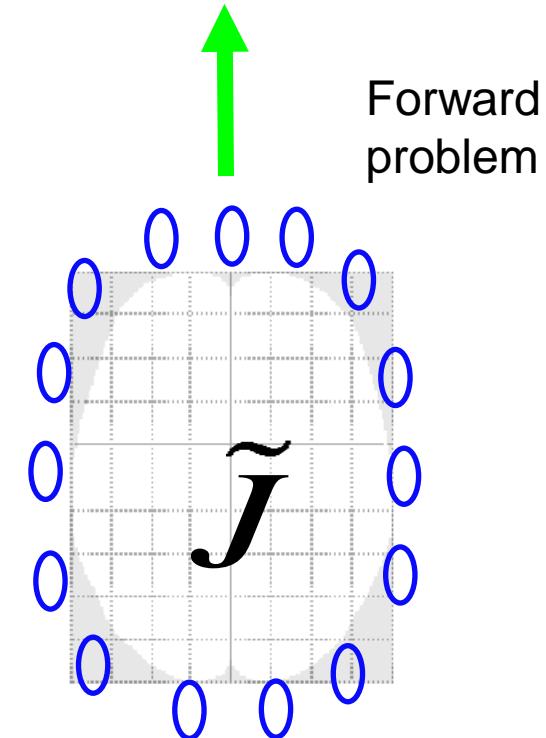
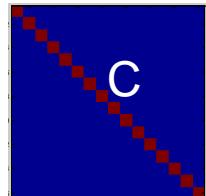
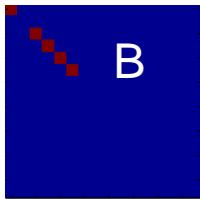


Prediction (\tilde{Y})

Inverse problem
Prior info (source covariance)

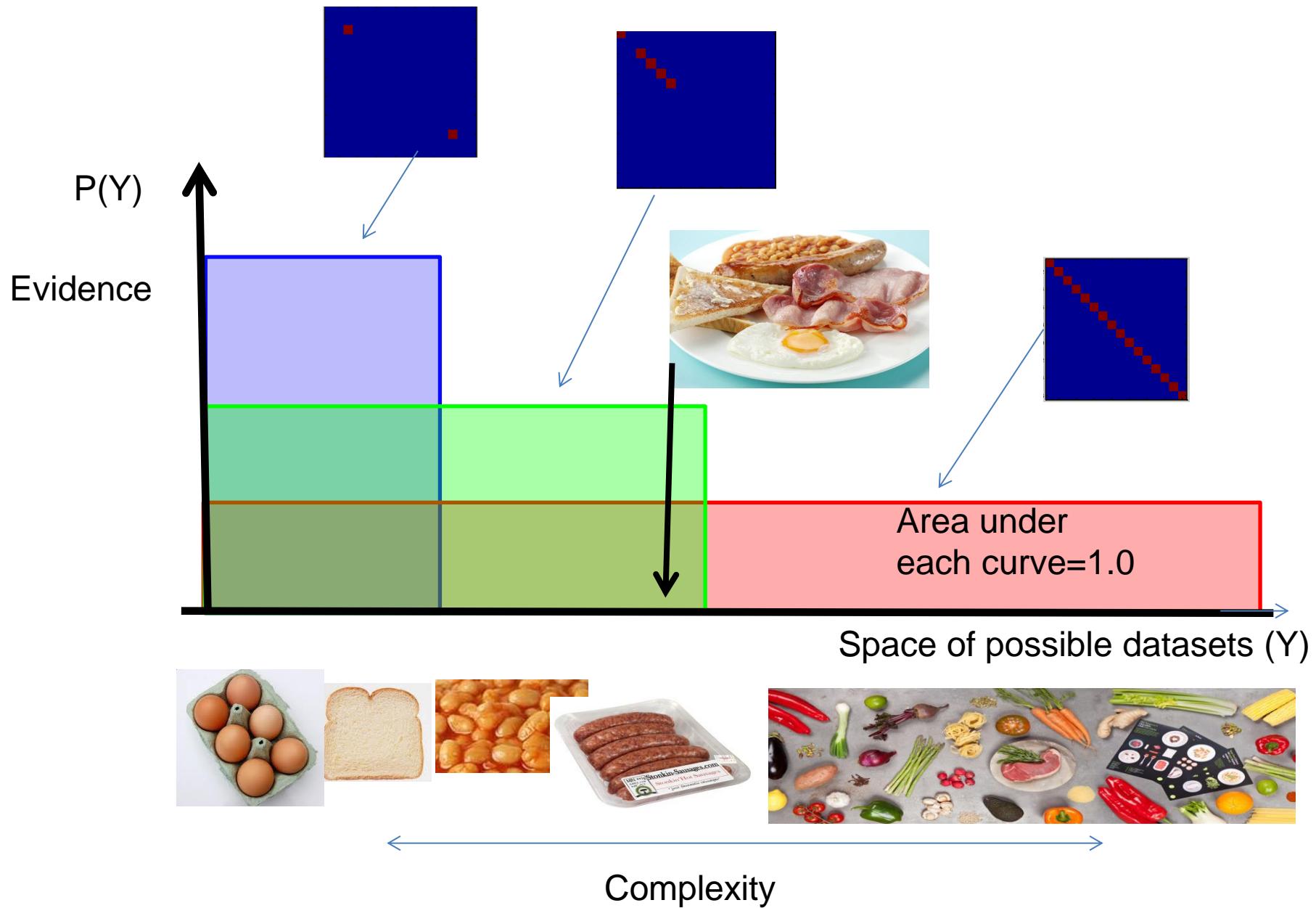


?



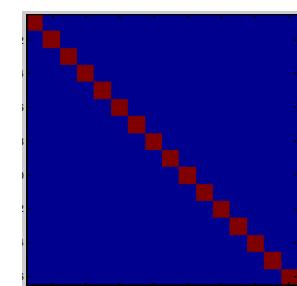
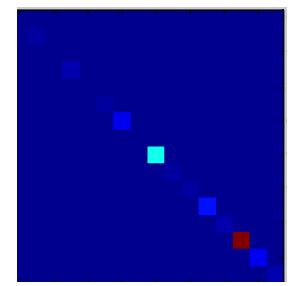
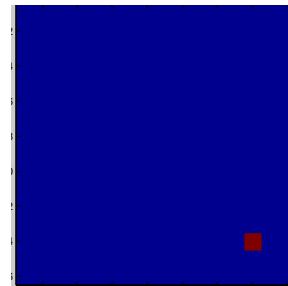
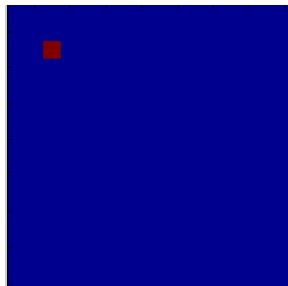
Forward problem

Consider 3 generative models

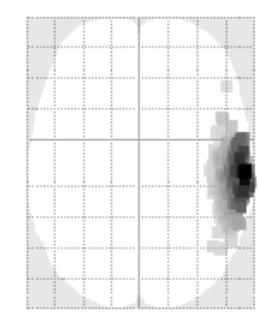
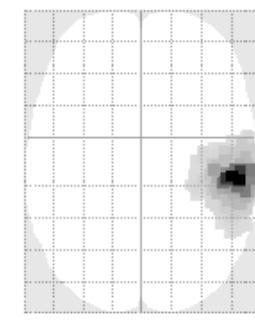
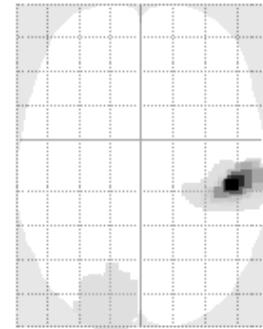
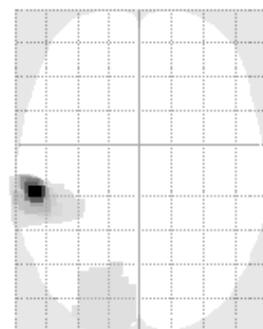


How do we chose between priors ?

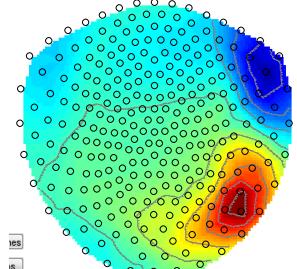
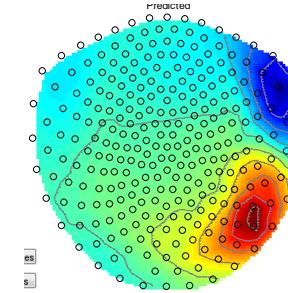
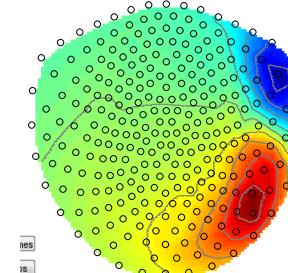
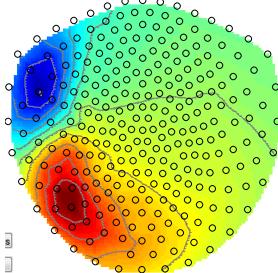
Prior



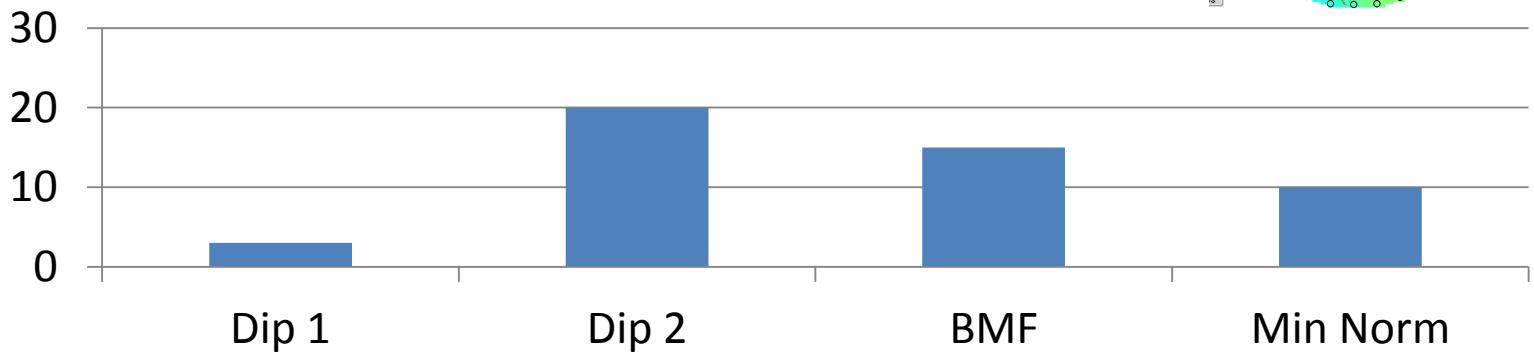
\tilde{J}



\tilde{Y}

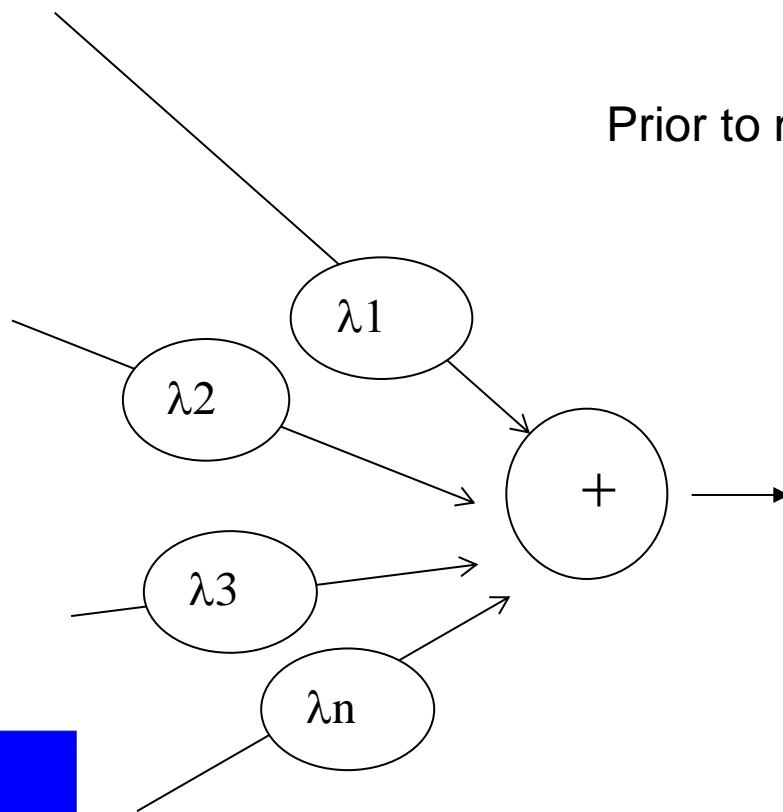
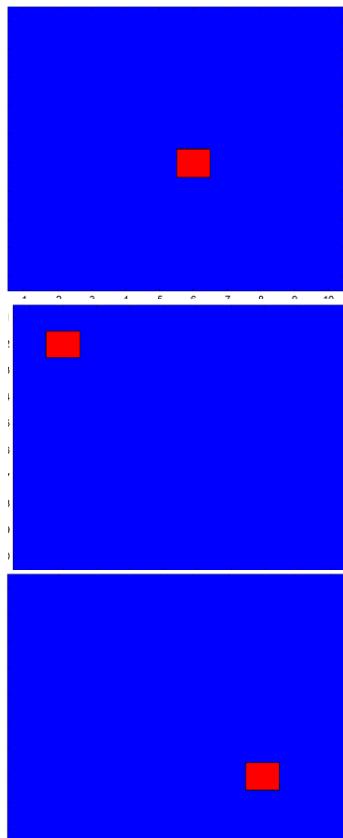


Log model evidence

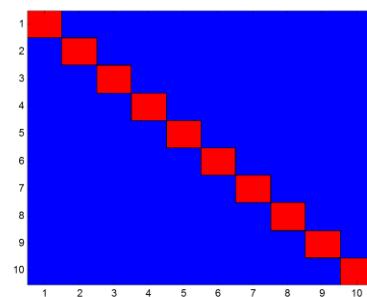
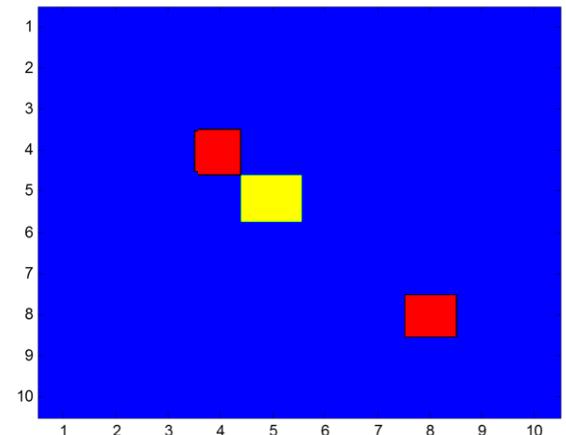


Multiple Sparse Priors (MSP), Champagne

Candidate Priors

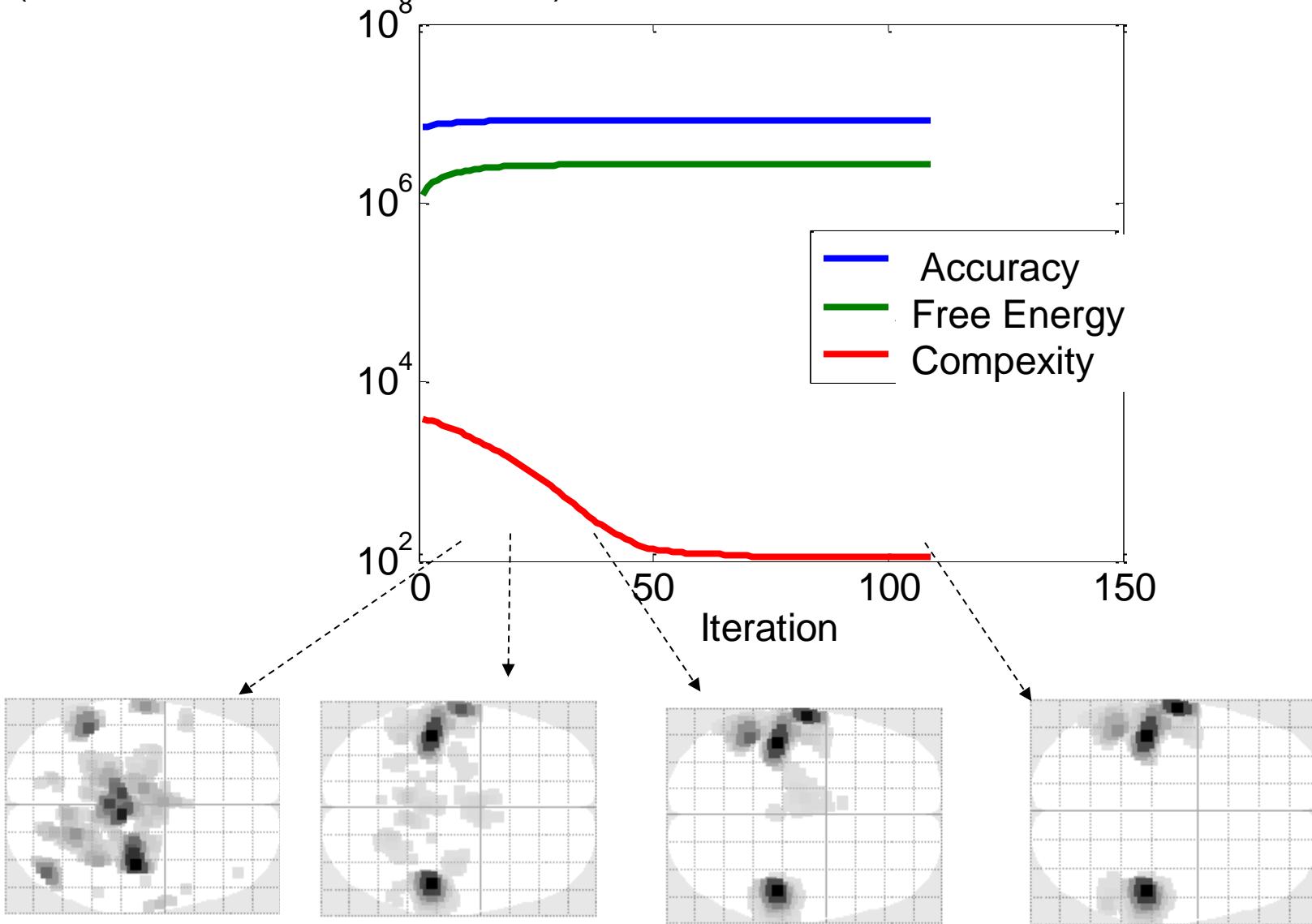


Prior to maximise model evidence



Multiple Sparse priors

So now construct the priors to maximise model evidence
(minimise cross validation error).



Conclusion

- MEG inverse problem can be solved easily with some prior knowledge.
- All prior knowledge encapsulated in a source covariance matrix.
- Can test between priors (or develop new priors) using Bayesian framework.

Thank you

- Karl Friston
- Jose David Lopez
- Vladimir Litvak
- Guillaume Flandin
- Will Penny
- Jean Daunizeau
- Christophe Phillips
- Rik Henson
- Jason Taylor
- Luzia Troebinger
- Chris Mathys
- Saskia Helbling

And all SPM developers

References

- [Mosher et al., 2003](#)
- J. Mosher, S. Baillet, R.M. Leahi
- **Equivalence of linear approaches in bioelectromagnetic inverse solutions**
- IEEE Workshop on Statistical Signal Processing (2003), pp. 294–297
- [Friston et al., 2008](#)
- K. Friston, L. Harrison, J. Daunizeau, S. Kiebel, C. Phillips, N. Trujillo-Barreto, R. Henson, G. Flandin, J. Mattout
- **Multiple sparse priors for the M/EEG inverse problem**
- NeuroImage, 39 (2008), pp. 1104–1120
- [Wipf and Nagarajan, 2009](#)
- D. Wipf, S. Nagarajan
- **A unified Bayesian framework for MEG/EEG source imaging**
- NeuroImage, 44 (2009), pp. 947–966

LONGER VERSION OF THIS TALK:

- <http://www.nottingham.ac.uk/conference/fac-sci/physics/meg-uk-conference/workshop.aspx>

Analytical approximation to model evidence

- Free energy= accuracy- complexity

$$F = -\frac{N_n}{2} \text{tr}(\Sigma_Y \Sigma^{-1}) - \frac{N_n}{2} \log |\Sigma| - \frac{N_n N_c}{2} \log 2\pi \\ - \frac{1}{2} (\hat{\lambda} - \nu)^T \Pi (\hat{\lambda} - \nu) + \frac{1}{2} \log |\Sigma_{\lambda} \Pi|$$

$$F = - \left[\begin{array}{c} \text{Model error} \\ \text{Size of model covariance} \end{array} \right] - \left[\begin{array}{c} \text{Num of data samples} \\ \text{Error in hyperparameters} \end{array} \right] + \left[\begin{array}{c} \text{Error in covariance of hyperparameters} \end{array} \right].$$