

Data model for distributed source estimates

$$M = G_1 X_1 + G_2 X_2 + ... + G_n X_n + noise$$

n is typically large (> # channels)

 $M = (G_1X_1 + G_2X_2 + ... + G_nX_n) + noise$

M = G X + noise

X' = W M, where W ensures $\min_{X} \{ || M - G \cdot X ||^2 + \lambda \cdot || X ||^2 \}$

Data model for spatial filtering

 $M = G_1 X_1 + G_2 X_2 + ... + G_n X_n + noise$

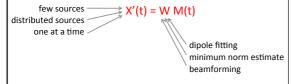
any number of n

 $M = (G_1X_1 + G_2X_2 + ...) + G_nX_n + (noise)$

 $X'_{n} = W_{n} M$, where $W^{T} = [G_{n}^{T} C_{M}^{-1} G_{n}]^{-1} G_{n}^{T} C_{M}^{-1}$

Data model to estimate source timeseries

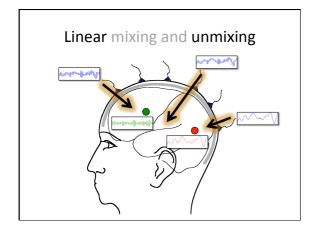
$$\mathsf{M} = \mathsf{G}_1 \mathsf{X}_1 + \mathsf{G}_2 \mathsf{X}_2 + \ldots + \mathsf{G}_n \mathsf{X}_n + \mathsf{noise}$$



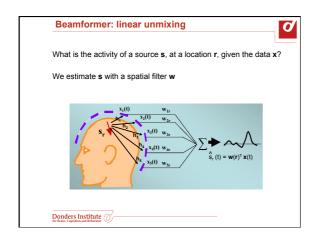
Data model to estimate spectral representations $M = G_1 X_1 + G_2 X_2 + ... + G_n X_n + \text{noise}$

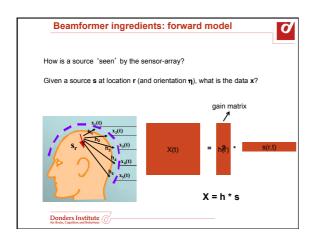
few sources distributed sources one at a time
$$X'(f) = WM(f)$$
 dipole fitting minimum norm estimate beamforming

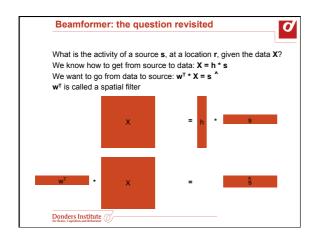
Linear mixing and unmixing

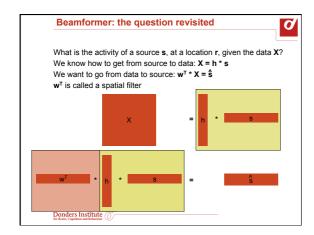


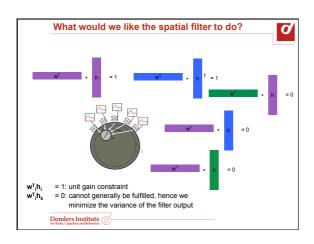
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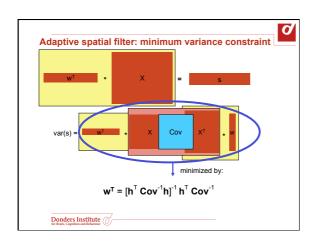


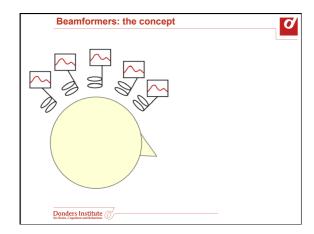


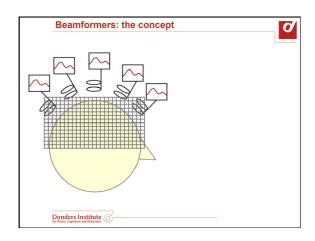


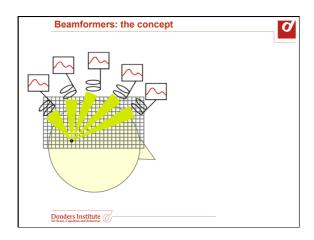


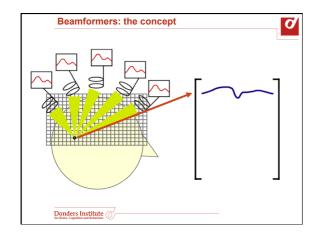


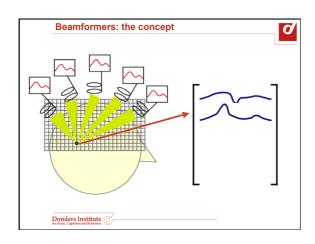


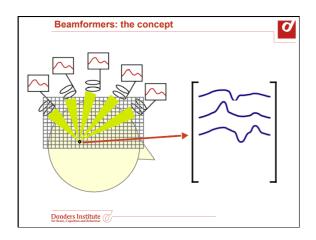




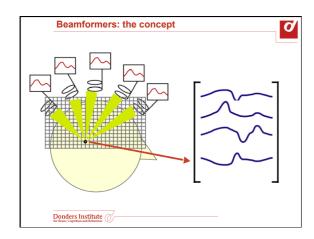


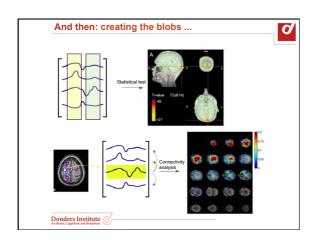


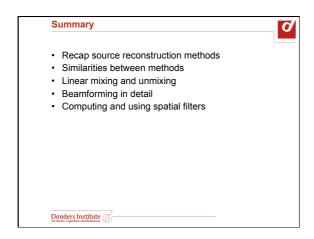




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orials
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